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Railway applications – Braking – Calculations for the estimation of stopping distance for specific Wheel Slide Protection testing

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TECHNICAL REPORT

CEN/TR 17315

RAPPORT TECHNIQUE

TECHNISCHER BERICHT

March 2019

ICS 45.040

English Version

**Railway applications - Braking - Calculations for the
estimation of stopping distance for specific Wheel Slide
Protection testing**

Applications ferroviaires - Freinage - Calculs pour
l'estimation des distances d'arrêt pour les essais
spécifiques aux dispositifs d'anti-enrayage

Bahnanwendungen - Bremsen -
Bremswegberechnungen für den Schleuderschutz

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European foreword

This document (CEN/TR 17315:2019) has been prepared by Technical Committee CEN/TC 256 “Railway applications”, the secretariat of which is held by DIN.

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Introduction

EN 15595 for Wheel Slide Protection (WSP) provides methods for testing a WSP system (Clause 7) and criteria for the evaluation of its performance under test (Clause 8). This includes tests and evaluation of the stopping performance of a vehicle/train with the WSP system fitted, carried out as track tests or on a WSP simulator.

For the evaluation of stopping performance during slide tests (see 8.3), the standard specifies the maximum permitted stopping distance extension for a vehicle/train, measured as a percentage of its dry rail stopping distance (Table 8). The maximum extension values are derived from estimations of the wheel/rail adhesion improvement produced by the operation of the WSP system and the associated vehicle stopping distances expected in the slide tests, calculated as detailed in this document.

1 Scope

This document gives guidelines for the calculation of vehicle stopping distances when testing a WSP system using the methods specified in EN 15595, the standard for Wheel Slide Protection, under the conditions defined in that standard.

This document is only applicable to the calculation of stopping distances for the evaluation of the results of WSP tests carried out in accordance with EN 15595.

This document does not apply to calculations used to determine the stopping performance of a WSP equipped train under operational conditions as it is only applicable for specific WSP test conditions.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

EN 14478, *Railway applications — Braking — Generic vocabulary*

EN 15595:2018, *Railway applications — Braking — Wheel slide protection*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in EN 14478 and the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- IEC Electropedia: available at <http://www.electropedia.org/>
- ISO Online browsing platform: available at <http://www.iso.org/obp>

3.1

adhesion profile

predefined set of data representing the adhesion characteristics of a section of running line

3.2

dry rail

conditions where 100 % of the brake force of the vehicle can be applied with no wheelset sliding more than 2 %

3.3

dry rail stopping distance

actual measured stopping distance in dry rail conditions

3.4

low adhesion

conditions where the wheel/rail adhesion is in the range 0,08 to 0,05

3.5

very low adhesion

conditions where the wheel/rail adhesion is in the range 0,05 to 0,03

3.6

extremely low adhesion

conditions where the wheel/rail adhesion is below 0,03

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3.7

slide test

test performed under low, very low and extremely low adhesion conditions

3.8

drag test

test to simulate braking on a falling gradient, performed with an auxiliary tractive unit to achieve a constant speed with a constant brake application

4 Symbols and abbreviations

For the purpose of this document, the following symbols and abbreviations apply.

Table 1 — Symbols

Symbol	Definition	Unit
g	Acceleration due to gravity	m/s^2
v_{ref}	WSP vehicle reference speed	km/h
v_t	True train speed	km/h
τ_x	Wheel/rail adhesion coefficient	—
τ	Initial adhesion coefficient	—
WSP	Wheel slide protection	—

5 Calculations

5.1 Wheel/rail adhesion improvement

5.1.1 General

The formulae in this clause are means that give an indication for the stopping distance that can be achieved by a certain trainset with low adhesion.

The formulae take into account different characteristics of the vehicle that are tested and are a practicable compromise to evaluate track tests.

The formulae cannot give exact values for the stopping distance in true conditions. Therefore each result is evaluated according to the flow chart given in EN 15595:2018, Figure 4.

5.1.2 Stopping distance calculation

The theoretical stopping distance for a vehicle with speed dependent retardation rates is shown below (see Formula (1)):

$$s = v_0 \times \left(t_a + \frac{t_{ab}}{2} \right) + \frac{(v_0)^2 - (v_1)^2}{2\tau_{ave,0} \times g} + \dots + \frac{(v_x)^2}{2\tau_{ave,x} \times g} \tag{1}$$

where

- s is the stopping distance, expressed in m;
- t_a is the delay time from the start of braking until the brake starts filling, expressed in s;
- t_{ab} is the build-up time of the brake cylinder pressure up to 95 % of the maximum pressure, expressed in s;
- v_0 is the initial vehicle speed, expressed in m/s;
- v_1 to v_x are the speeds at the different brake forces, expressed in m/s;
- $\tau_{ave,0}$ to $\tau_{ave,x}$ are the average wheel/rail adhesions required for each speed range and calculated from Formula (2).

The average wheel/rail adhesion required for each speed range τ_{ave} is calculated as set out in Formula (2).

$$\tau_{ave} = \frac{m_1}{m_{total}} \times \tau_1 + \dots + \frac{m_n}{m_{total}} \times \tau_n \quad (2)$$

where

- τ_1 to τ_n are the wheel/rail adhesions that provide the effective brake force between wheel and rail on each of the wheelsets;
- m_1 to m_n are the axle loads of the wheelsets;
- m_{total} is the total static mass on all the wheelsets;
- n number of wheelsets.

For unbraked wheelsets τ_i is set to zero, for braked wheelsets τ_i is taken from the brake calculation:

where

- τ_i is the τ of the wheelsets number i , where i is between 1 and n .

Examples of the use of these formulae are shown in Annex A.

5.1.3 Dry rail conditions

The actual measured stopping distance in dry conditions, with WSP operational, is the stopping distance corresponding to the nominal performance required for the vehicle within the specified tolerances.

$\tau_{ave,dry}$ is calculated from Formula (2) for dry rail conditions.

The friction coefficients $\tau_{i,dry}$ should be taken from the brake calculation, updated after the brake distance measurement. If the measured frictional coefficient depends on the initial speed, the mean frictional coefficient for the different speed classes can be used.

5.1.4 Low adhesion

The aim of the WSP under low adhesion conditions is to improve the levels of wheel/rail adhesion experienced by the wheelsets by attempting to control at an absolute slide of up to 30 km/h at speeds greater than 40 km/h.

Wheel/rail adhesion improvement is measured using WSP equipment alone, without any other adhesion enhancing equipment such as magnetic track brake, sanding, etc.